

```
1 import CoDrone
2
3 drone = CoDrone.CoDrone()
4 drone.pair("9545")
5 drone.takeoff()
6
7 # set_roll - going left(-100) of right(100)
8 # power how much power to go left or right
9 drone.set_roll(-30)
10 drone.move(1)
11 drone.set_roll(30)
12 drone.move(1)
13
14 # set_pitch - going forward(100) or backward(-100)
15 # power how much power to go forward or backward
16 drone.set_pitch(30)
17 drone.move(1)
18 drone.set_pitch(-30)
19 drone.move(1)
20
21 # set_yaw - spins/turns right(100) or left(-100)
22 # power how much power to spin/turn left or right
23 drone.set_yaw(-25)
24 drone.move(4)
25 drone.set_yaw(25)
26 drone.move(4)
27
28 # set_throttle - going upward(100) or downward(-100)
29 # power how much power to go upward or downward
30 drone.set_throttle(50)
31 drone.move(1)
32 drone.set_throttle(-50)
33 drone.move(1)
34
35 drone.land()
36 drone.close()
37
```