

```
1 import CoDrone
2
3 drone = CoDrone.CoDrone()
4 drone.pair("9545")      # pairs to drone
5
6 # drone.arm_off()
7 # drone.eye_off()
8 drone.set_all_led(255, 255, 255, 100)
9
10 drone.takeoff()        # takeoff for 2 seconds
11 drone.hover(3)         # hover for 3 seconds
12
13 drone.set_pitch(10)    # goes forward at 10% power
14 drone.move(2)          # moves forward for 2 seconds
15
16 drone.land()           # lands rover
17
18 drone.takeoff()        # takeoff for 2 seconds
19 drone.hover(3)         # hover for 3 seconds
20
21 drone.set_yaw(10)      # spins right at 10% power
22 drone.move(2)          # spins/turns right for 2
    seconds
23
24 drone.set_pitch(10)    # goes forward at 10% power
25 drone.move(2)          # moves forward for 2 seconds
26
27 drone.land()           # lands drone
28 drone.close()          # disconnects CoDrone
29
```